MATH 170A Summer Session II 2024

Discussion 4

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TA: Kejin Wu

1 Definition reviews

1.1 Matrix and vector norms

Definition 1.1 (Vector norm). A norm on \mathbb{R}^n is a function that assigns to each $x \in \mathbb{R}^n$ a nonnegative real number ||x||, called the norm of x, such that the following four properties are satisfied for all $x, y \in \mathbb{R}^n$ and all $\alpha \in \mathbb{R}$:

$$\begin{aligned} \|x\| &\geq 0, \forall x \in \mathbb{R}^n \\ \|x\| &= 0 \text{ implies } x = 0 \\ \|\alpha x\| &= |\alpha| \|x\| \\ \|x + y\| &\leq \|x\| + \|y\| \text{ (triangle inequality)} \end{aligned}$$

Theorem 1.2 (Cauchy-Schwarz inequality). *For all* $x, y \in \mathbb{R}^n$ *, we have*

$$\left|\sum_{i=1}^{n} x_i y_i\right| \le \left(\sum_{i=1}^{n} x_i^2\right)^{1/2} \left(\sum_{i=1}^{n} y_i^2\right)^{1/2}$$

Definition 1.3 (Matrix norm). A matrix norm is a function that assigns to each $A \in \mathbb{R}^{n \times n}$ a real number ||A||, called the norm of A. Specifically, for all $A, B \in \mathbb{R}^{n \times n}$ and all $\alpha \in \mathbb{R}$,

$$\begin{split} \|A\| &\ge 0 \\ \|A\| &= 0 \text{ implies } A = 0 \\ \|\alpha A\| &= |\alpha| \|A\| \\ \|A + B\| &\le \|A\| + \|B\| \\ \|AB\| &\le \|A\| \|B\| \quad (operator norm) \end{split}$$

Definition 1.4 (Induced matrix norm). *The matrix norm induced by a vector norm* $\|\cdot\|_v$ *is defined by*

$$||A||_M = \max_{x \neq 0} \frac{||Ax||_v}{||x||_v}$$

Exercise 1.5. Show that $\sqrt{tr(A^TA)}$ defines a matrix norm function.

Exercise 1.6. Show that $||x||_1 \le \sqrt{n} ||x||_2$.

1.2 Condition number

Definition 1.7 (Condition number (informal)). Condition number is a useful measure of the sensitivity of the linear system Ax = b. For example, if there is a perturbation in the b vector, i.e., we actually have $b + \delta b$. δb could be some rounding error when the vector b is stored in computer.

We are interested in exploring if $||\delta x|| / ||x||$ is also small when $||\delta b|| / ||b||$ is small.

The condition number of a matrix A is:

$$\kappa(A) = ||A|| ||A^{-1}|| \ge 1.$$

Theorem 1.8. Let A be nonsingular, and let x and $\hat{x} = x + \delta x$ be the solutions of Ax = b and $A\hat{x} = b + \delta b$, respectively. Then

$$\frac{\|\delta x\|}{\|x\|} \le \kappa(A) \frac{\|\delta b\|}{\|b\|}$$

Definition 1.9 (maximum and minimum magnification).

$$\max(A) = \max_{x \neq 0} \frac{\|Ax\|}{\|x\|} = \|A\|$$

and

$$\operatorname{minmag}(A) = \min_{x \neq 0} \frac{\|Ax\|}{\|x\|}$$

Thus, we have:

$$\kappa(A) = \frac{\max(A)}{\min(A)}$$

Proposition 1.10.

 $\max(A) = \frac{1}{\min(A^{-1})} \quad and \quad \max(A^{-1}) = \frac{1}{\min(A)}$

From textbook:

An ill-conditioned matrix is one for which the maximum magnification is much larger than the minimum magnification.

If the matrix A is nonzero but singular, then there exists $x \neq 0$ such that Ax = 0. Thus $\min(A) = 0$, and it is reasonable to say that $\kappa(A) = \infty$. That is, we view singularity as the extreme case of ill-conditioning. Reversing the viewpoint, we can say that an ill-conditioned matrix is one that is "nearly" singular.

Exercise 1.11. Using 1-norm, find the condition number of the following matrix, where $0 < \varepsilon < 1$:

$$A = \left[\begin{array}{cc} 1 & 0 \\ 1 & \varepsilon \end{array} \right]$$

Explain what happens to the condition number $\kappa(A)$ *, when* ε *varies*

Exercise 1.12. Let $A = \begin{bmatrix} 1001 & 1000 \\ 1000 & 1001 \end{bmatrix}$. Find nonzero vectors $b, \delta b, x, \delta x$ such that Ax = b $A(x + \delta x) = b + \delta b$ and the product $\frac{\|\delta x\|_{\infty}}{\|x\|_{\infty}} \cdot \frac{\|b\|_{\infty}}{\|\delta b\|_{\infty}}$ is maximum.